

Computing systems for ALICE/LHC: run3 and beyond

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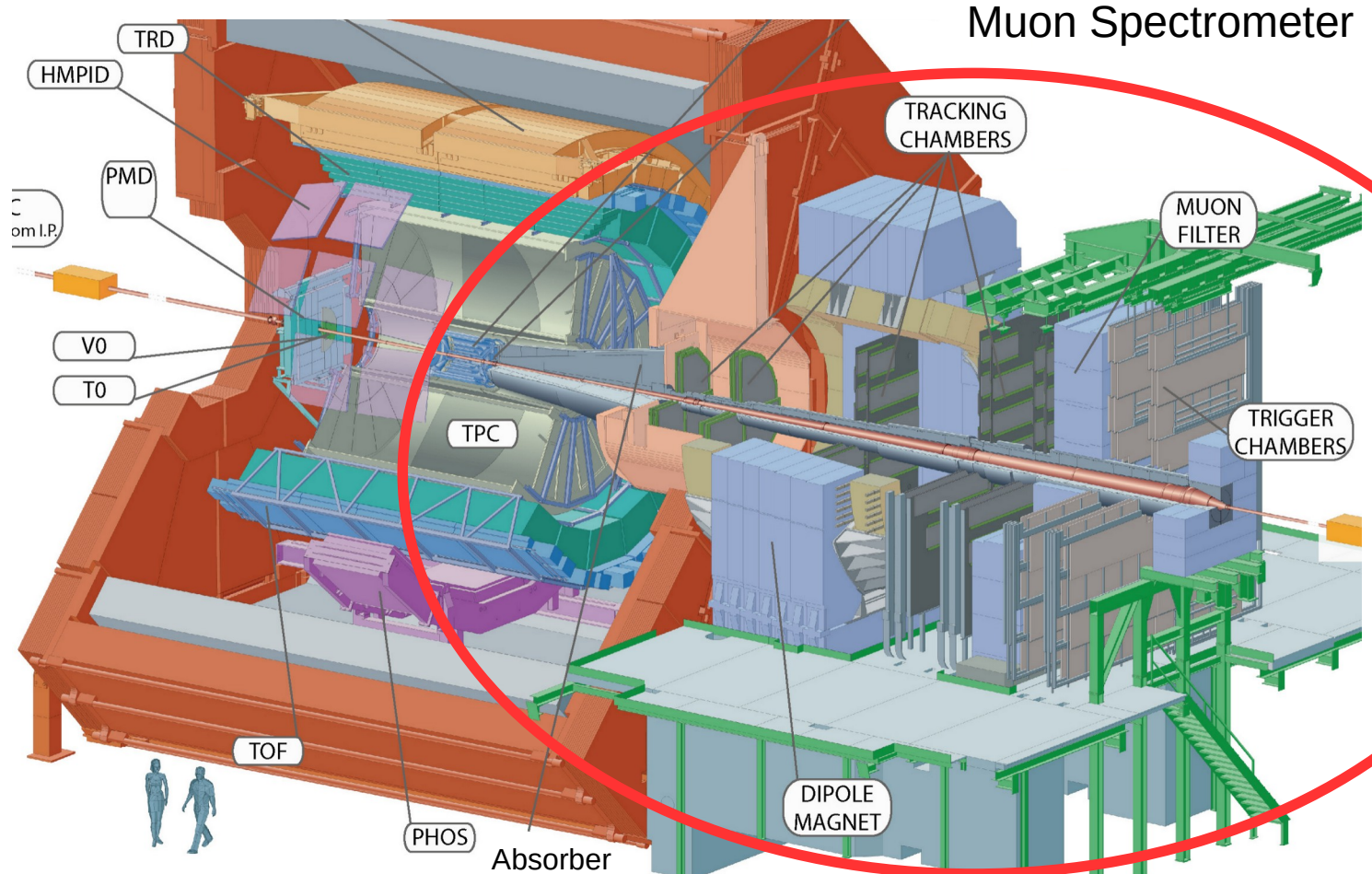
GEFAE
IF/UFRGS

Workshop RENAF AE 2021
13th July 2021

- Forward tracking in ALICE
 - Muon Spectrometer
 - Muon Forward Tracker
 - Run5 and beyond
- ALICE O2: ALICE On-line Off-line computing system
 - Forward tracking data model, tracking classes

ALICE/LHC - A Large Ion Collider Experiment

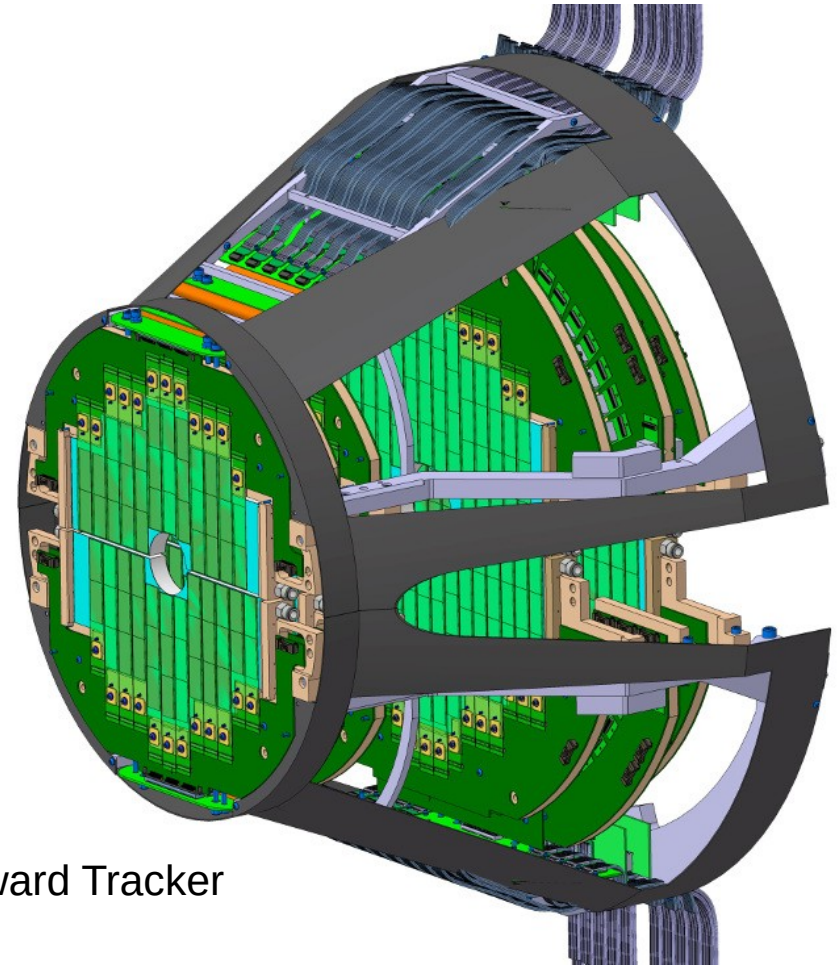
- Quark-Gluon Plasma



Muon Spectrometer

Muon Forward Tracker

- Forward pseudorapidity: $-3.6 < \eta < -2.45$
- 5 disks / 10 active layers
- 936 ALICE Pixel Detectors (ALPIDE)
 - MAPS: Monolithic Active Pixel Sensors
- Improve vertexing resolution at forward
 - B mesons studies
 - prompt/non-prompt dimuon separation





ALICE

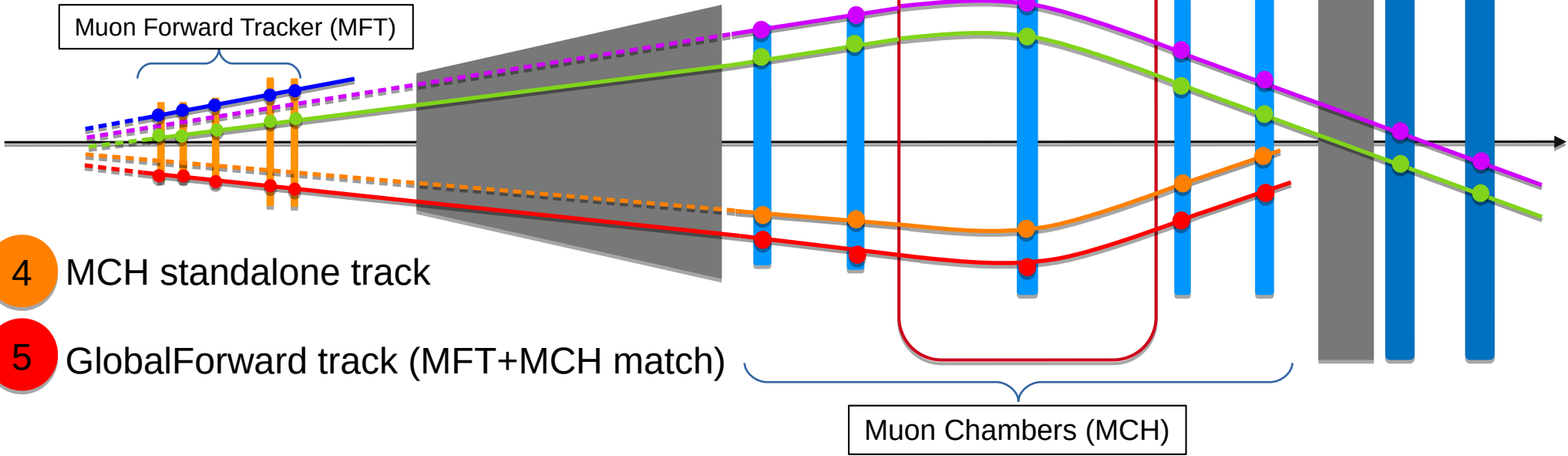
RUN3 forward tracks overview*



MFT

- 1 MUON standalone track (Run2: MCH + MID)
- 2 MFT standalone track
- 3 GlobalMuon track (MFT+MCH+MID match)

Muon Trigger (MTR): Run1,2
 Muon Identifier (MID) Run3+

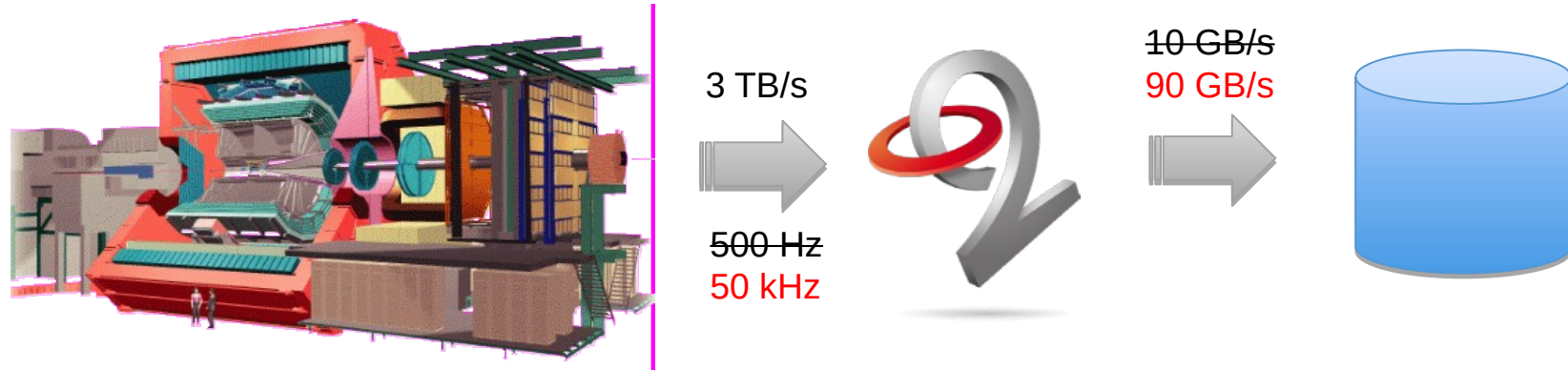


- 4 MCH standalone track
- 5 GlobalForward track (MFT+MCH match)

Online-Offline computing system

Run3 ALICE data taking objectives

- For Pb-Pb collisions:
 - Reach the target of $\pm 13 \text{ nb}^{-1}$ integrated luminosity in Pb-Pb for rare triggers.
 - The resulting data throughput from the detector has been estimated to be greater than 1TB/s for Pb–Pb events, roughly two orders of magnitude more than in Run 1



Challenges in forward tracking: new computing model at forward

- High multiplicity
 - Demand high efficiency tracking/reconstruction
 - New track model and dataformats at forward
- Matching MCH and MFT tracks
 - Separated by ~ 4 meters of graphite+concrete
- Performance studies for a new dedicated Heavy Ion Experiment at the LHC \rightarrow ALICE 3 LOI

Forward track model and Coordinate System

- Helix track model

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} x_0 - \frac{H_z}{(q/p_{t0})k} \sin(\phi_0) \cos\left(\frac{(q/p_{t0})\Delta zk}{\tan\lambda_0}\right) + \frac{H_z}{(q/p_{t0})k} \sin(\phi_0) + \frac{\cos(\phi_0)}{(q/p_{t0})k} \sin\left(\frac{(q/p_{t0})\Delta zk}{\tan\lambda_0}\right) \\ y_0 + \frac{H_z}{(q/p_{t0})k} \cos(\phi_0) \cos\left(\frac{(q/p_{t0})\Delta zk}{\tan\lambda_0}\right) - \frac{H_z}{(q/p_{t0})k} \cos(\phi_0) + \frac{\sin(\phi_0)}{(q/p_{t0})k} \sin\left(\frac{(q/p_{t0})\Delta zk}{\tan\lambda_0}\right) \\ \Delta z + z_0 \end{bmatrix}$$

$$k = 0.3 |B_z|$$

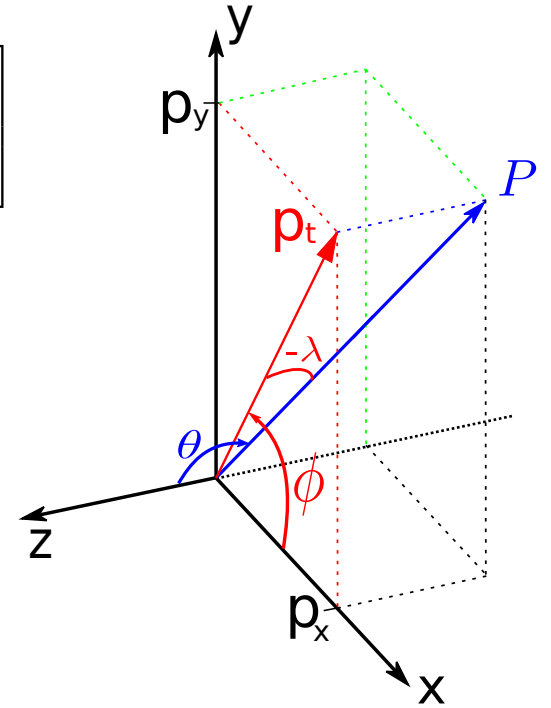
$$H_z = \frac{B_z}{|B_z|}$$

$$\theta = -\frac{(q/p_{t0})\Delta zk}{\tan\lambda_0}$$

- State vector / coordinate system: $\vec{s} = (x, y, \phi, \tan \lambda, q/p_t)$

- $\phi \rightarrow p_t$ direction (azimuth)

- $\lambda \rightarrow$ Complementary polar angle:



$$\lambda = \frac{\pi}{2} - \theta_{\text{Polar}}$$

- **TrackParCovFwd Class**
 - Data members: parameters & covariances matrix
 - Methods
 - Track propagation (analytic)
 - Multi coulomb scattering effects
 - Kalman filter update
- Used by MFT standalone tracks and GlobalMuonTracks
 - **Global Muon Tracks in separate repository**

Kalman filter:

'p_k: '

$$\begin{bmatrix} x_k \\ y_k \\ \phi_k \\ \tan\lambda_k \\ (q/p)_{tk} \end{bmatrix}$$

'm_k: '

$$\begin{bmatrix} x_m \\ y_m \end{bmatrix}$$

'V_k: '

$$\begin{bmatrix} \sigma_x^2 & 0 \\ 0 & \sigma_y^2 \end{bmatrix}$$

'H_k: '

$$\begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \end{bmatrix}$$

'h_k: '

$$\begin{bmatrix} x_m & 0 & 0 & 0 & 0 \\ 0 & y_m & 0 & 0 & 0 \end{bmatrix}$$

'K_k = CP*H_k.T*(V_k+H_k*CP*H_k.T).inv(): '

$$\begin{bmatrix} \frac{CP_{00}(CP_{11}^2 + \sigma_y^2)}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} - \frac{CP_{10}^2}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} - \frac{CP_{00}CP_{10}}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} + \frac{CP_{10}(\sigma_x^2 + CP_{00})}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} \\ - \frac{CP_{10}CP_{11}}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} + \frac{CP_{10}(\sigma_y^2 + CP_{11})}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} - \frac{CP_{10}^2}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} + \frac{CP_{11}(\sigma_x^2 + CP_{00})}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} \\ - \frac{CP_{10}CP_{21}}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} + \frac{CP_{20}(\sigma_y^2 + CP_{11})}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} - \frac{CP_{10}CP_{20}}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} + \frac{CP_{21}(\sigma_x^2 + CP_{00})}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} \\ - \frac{CP_{10}CP_{31}}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} + \frac{CP_{30}(\sigma_y^2 + CP_{11})}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} - \frac{CP_{10}CP_{30}}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} + \frac{CP_{31}(\sigma_x^2 + CP_{00})}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} \\ - \frac{CP_{10}CP_{41}}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} + \frac{CP_{40}(\sigma_y^2 + CP_{11})}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} - \frac{CP_{10}CP_{40}}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} + \frac{CP_{41}(\sigma_x^2 + CP_{00})}{-CP_{10}^2 + (\sigma_x^2 + CP_{00})(\sigma_y^2 + CP_{11})} \end{bmatrix}$$

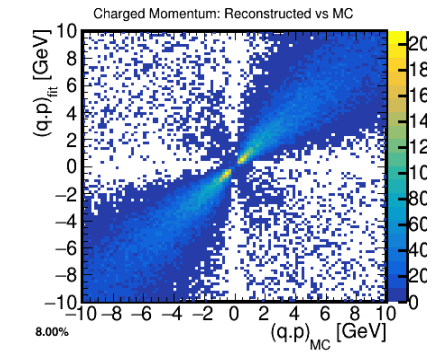
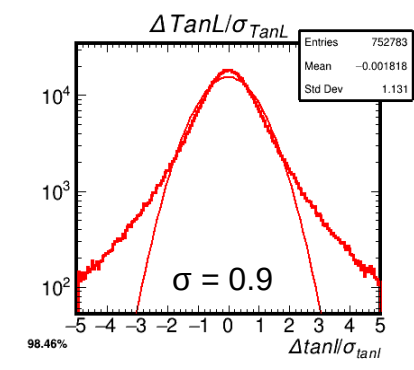
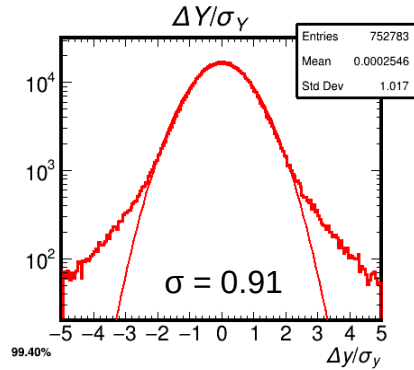
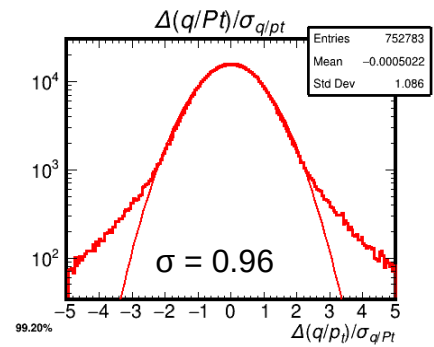
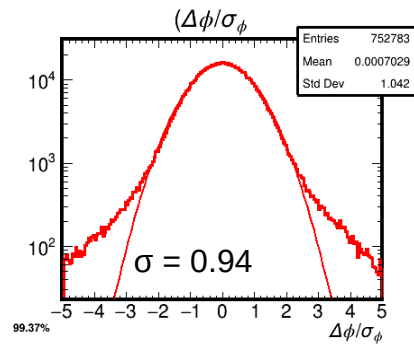
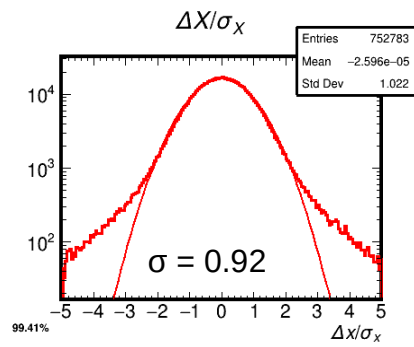
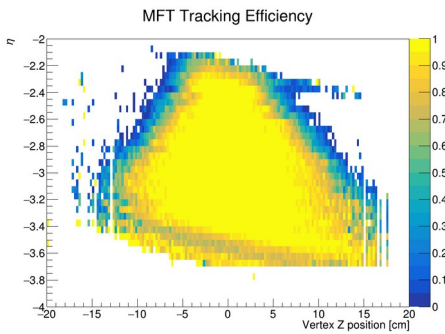
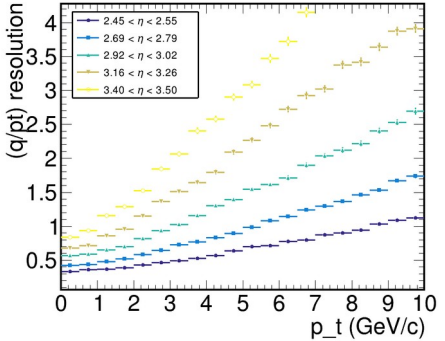
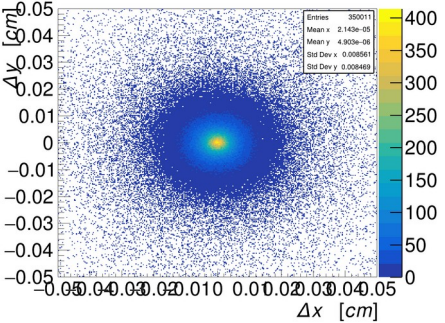


ALICE

MFT tracking performance evaluation

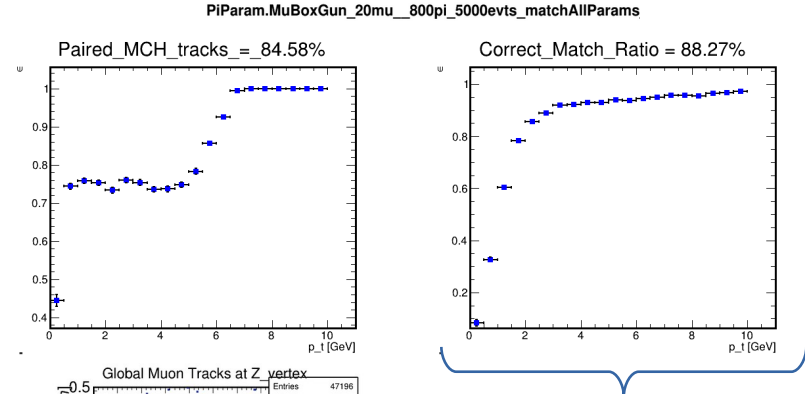
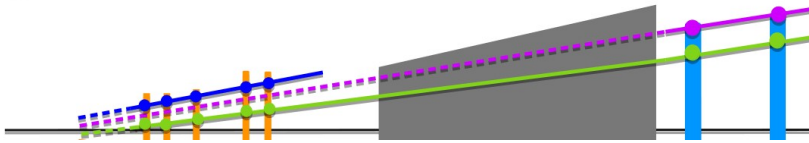


(WIP)



Global Muon Tracking

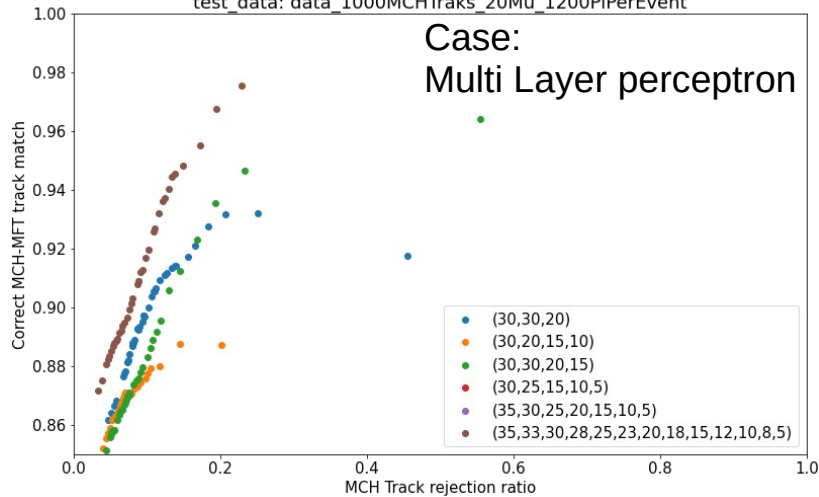
- 1 MUON standalone track (Run2: MCH + MID)
- 2 MFT standalone track
- 3 GlobalMuon track (MFT+MCH+MID match)



Chi² matching

training_data: data_50000MCHTraks_20Mu_10PiPerEvent
test_data: data_1000MCHTraks_20Mu_1200PiPerEvent

Case:
Multi Layer perceptron

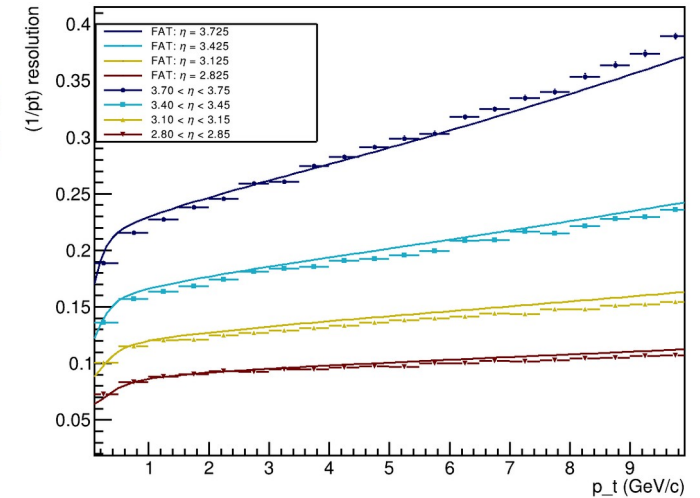
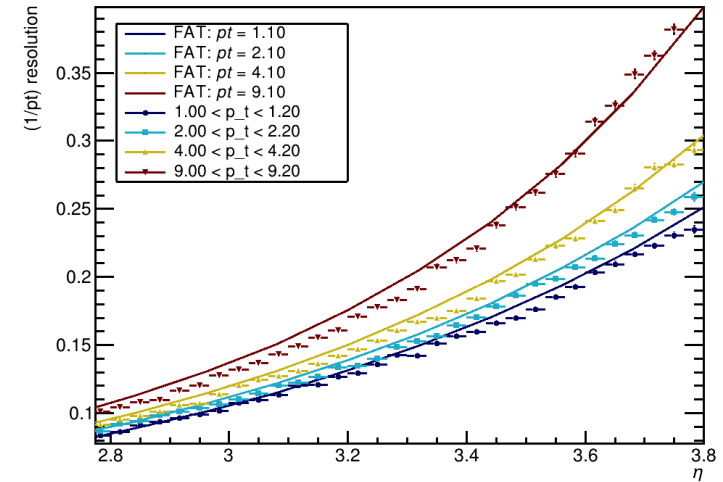
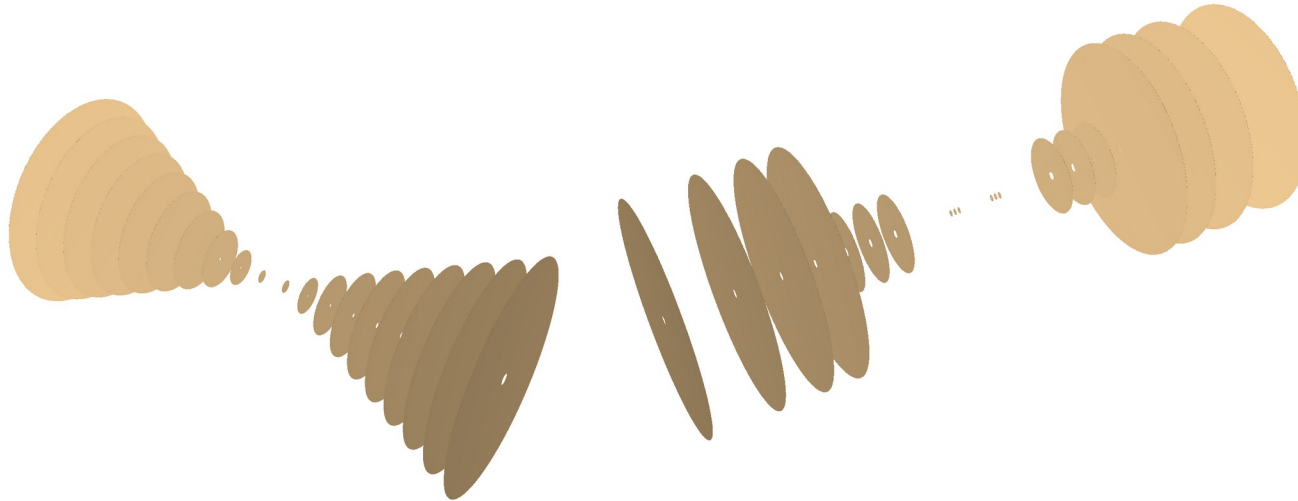


Machine Learning:

- Exploring novel applications of machine learning
 - track reconstruction and physics analysis
- Matching interface with ML Libraries
 - Root TMVA
 - SciLearn Kit

Forward tracker studies

- Performance evaluation and layout optimization of next generation tracker for RUN5 and beyond.



Summary

- ALICE/LHC demands a new computing system for run3 and beyond
- GEFAE is exploring the limits of forward tracking by addressing several forward-related computing challenges for ALICE
 - Track model, reconstruction, track matching, machine learning
 - ALICE 3 LOI



Backup slides



Physics interest for each topology of forward tracks (run3+)

- 1 • MUON standalone tracks (MCH+MID) → Any muon-based analysis in the “Run1+2” style.
- 2 • MFT standalone tracks (MFT only: any charged particle) → Multiplicity analyses, underlying event characterization at forward rapidity, UPC, ...
- 3 • Global Muon Tracks (MFT+MCH+MID) → Any muon-based analysis in the “Run3+4” style.
- 4 • Particular case 1: MCH tracks without MID identification and without MFT information. Possible use: analyses targeting very soft muons, e.g. dimuon observables at vanishing p_T in ultra-peripheral collisions.
- 5 • Particular case2: MCH+MFT tracks without MID identification. Possible use: as before, but with improved mass resolution for low-mass resonances and a better correction for the absorber effects.